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INTERNAL PRESSURE MEASUREMENTS FOR A LIQUID PAYLOAD AT LOW REYNOLDS NUMBERS

DAVID J. HEPNER KEITH P. SOENCKSEN BRADFORD S. DAVIS NICHOLAS G. MAIORANA

JUNE 1988



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David J. Hepner		(301)-278-	2533	1 SLC	BR-LF-A

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TABLE OF CONTENTS

		<u>Page</u>
	ACKNOWLEDGMENTS	iii
	LIST OF FIGURES	vii
	LIST OF TABLES	viii
I.	INTRODUCTION	1
II.	EXPERIMENT DESCRIPTION AND OBSERVATIONS	2
II.	DATA REDUCTION	4
IV.	CONCLUSIONS	7
	LIST OF REFERENCES	51
	LIST OF SYMBOLS	53
	DISTRIBUTION LIST	55

LIST OF FIGURES

Figure		Page
1	Cubic spline fit to experimental data for various high Reynolds number cases (Ref. 2)	. 8
2	Cylinder dimensions and transducer locations	9
3	Forced precession gyroscope apparatus	10
4	Precession angle adjustment cam	11
5	Pressure gage calibration for $r/a = 0.667$	12
6	Instrumentation schematic	13
7	High pass filter amplifier transfer function	14
8	Liquid viscosity measurements and logarithmic function fit	15
9	Absolute pressure decrease on an end wall for a slow spin-up	16
10	Absolute pressure rise for extended running time, (coning rate = 5 Hz, spin rate = 70 Hz)	17
11	Spectral response for oscillatory pressures	18
12	Spectra of several runs overlayed for low Reynolds number	19
13	Prograde pressure coefficient data for two radial positions (r/a = 0.434 and 0.667 at Re near 8.8, α = 2.25°)	20
14	Prograde and retrograde pressure coefficient comparison with modified Ref. 3 data for Re near 8.8, α = 2.00°, r/a = 0.667	21
15	Experimental prograde data (f = .92), Δ = 0.022°, \Box = 0.051°, x = 0.105°, \diamondsuit = 0.22°, z = 0.50° (Ref. 2)	22
16	Prograde and retrograde pressure coefficient comparison for linearity with coning angle, Re = 7.3, α = 0.5, 1 and 2 deg, r/a = 0.667	23
17	Expanded coning frequency and error ranges due to low spin rates	24
18	Prograde and retrograde pressure coefficient data for Re = 5.2, α = 2.00°, r/a = 0.667	25
19	Prograde and retrograde pressure coefficient data for Re = 3.1, α = 2.00°, r/a = 0.667	26
20	Comparison of experimental data to two available low Reynolds number theories for Re = 3.1	27

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LIST OF FIGURES (continued)

Figure		Page
21	Comparison of experimental data to two available low Reynolds number theories for Re = 8.7	28
	LIST OF TABLES	
Table		Page
1	Cavity Dimensions of Lucite Cylinder with Various Inserts	29
2	Reynolds Number Calculations for Available Spin Rates and Actual Liquid Viscosities for an Internal Cylinder Radius of 3.176 cm	30
3	Absolute Pressure Measurements and Predicted Pressure Differences for Constant Spin Rates	31
4	Absolute Pressure Measurements for Constant Spin (70 Hz) and Coning Motion (5 Hz)	32
5	Forced Precession Gyroscope System Errors	33
6a	Prograde Oscillatory Pressure Data for Re = 8.7, α = 2.25°, r/a = 0.667	34
6b	Prograde Oscillatory Pressure Data for Re = 8.7, α = 2.25°, r/a = 0.434	35
7 a	Prograde Oscillatory Pressure Data for Re = 8.7, α = 2.00°, r/a = 0.667	36
7b	Retrograde Oscillatory Pressure Data for Re = 8.7, α = 2.00°, r/a = 0.667	37
8a	Prograde Oscillatory Pressure Data for Re = 7.3, α = 0.50°, r/a = 0.667	38
86	Retrograde Oscillatory Pressure Data for Re = 7.3, α = 0.50°, r/a = 0.667	39
9a	Prograde Oscillatory Pressure Data for Re = 7.3, α = 1.00°, r/a = 0.667	40
9b	Retrograde Oscillatory Pressure Data for Re = 7.3, α = 1.00°, r/a = 0.667	41
10a	Prograde Oscillatory Pressure (lata for Re = 7.3, α = 2.00°, r/a = 0.667	42

LIST OF TABLES (continued)

Table		Page
106	Retrograde Oscillatory Pressure Data for Re = 7.3, α = 2.00°, r/a = 0.667	. 43
11a	Prograde Oscillatory Pressure Data for Re = 5.2, α = 2.00°, r/a = 0.667	. 44
116	Retrograde Oscillatory Pressure Data for Re = 5.2, α = 2.00°, r/a = 0.667	45
12a	Prograde Oscillatory Pressure Data for Re = 3.1, α = 2.00°, r/a = 0.667	. 46
12b	Retrograde Oscillatory Pressure Data for Re = 3.1, α = 2.00°, r/a = 0.667	. 47
13	Comparison of Experimental Data to Two Available Low Reynolds Number Theories for Re = 3.1	. 48
14	Comparison of Experimental Data to Two Available Low Reynolds Number Theories for Re = 8.7	. 49

I. INTRODUCTION

Spin-stabilized projectiles can experience poor flights due to the influence of liquid payloads. Substantial analytical and numerical work has been done on this problem, but quality experimental data on the primitive variables of the liquid (pressure and velocity) are still required to evaluate the accuracy and applicability of models and codes.

Scaled laboratory experiments simulating spin-stabilized, liquid-filled cylinders and comparisons with theory have been reviewed by Sedney. The history of experimental pressure measurements at the US Army Ballistic Research Laboratory (BRL), Aberdeen Proving Ground, Maryland has included many scaled simulations in a small, forced precession gyroscope fixture. Whiting reported liquid pressure measurements for a range of relatively high Reynolds numbers (5,000 to 500,000). For high Reynolds number cases, Whiting found that the liquid behaves in a resonant manner where a maximum pressure coefficient was found by varying the ratio of coning to spin frequencies (τ) . Measured and computed pressures were compared for very small angles of attack (typically less than 1 degree). Figure 1 represents a cubic spline fit to experimental data from Reference 2. Nonlinear and aperiodic pressures were also observed, but few general conclusions were made. Using the same techniques, a single series of measurements were completed by Nusca, Beims, and D'Amico for a Reynolds number of 8.8.3 They found pressure responses to be almost linear with τ . Experimentally, the linearity with coning frequency at lower Reynolds numbers may be a result of the resonance curve broadening and flattening with increased viscous forces. Hence, for very low Reynolds numbers the linear results tend to occur over a small range of a resonance Cone-up pressure data were documented for a single cylinder aspect ratio, geometry and Reynolds number. 4 Other laboratory experiments simulating spin-stabilized, liquid-filled projectiles have been performed by D'Amico⁵ to examine liquid coning for low Reynolds numbers. In D'Amico's experiments with Reynolds numbers greater than 1,000, the transverse moment of inertia of a free gyroscope was varied to find the frequency of motion where maximum coning growth would occur, i.e., a resonance peak. In free gyroscope tests for Reynolds numbers less than 100, the broadening effect of low Reynolds numbers is also evident. Evidence of related liquid instabilities for actual flight data was reported in References 6-8. Recently, a full- scale three-degree-offreedom flight simulator was used to examine both endwall and sidewall pressure fluctuations, as well as the phase relationship between the maximum pressure and cylinder orientation for a high Reynolds number of 18,200. 9-10

Typically, pressure responses are resonant in nature for Reynolds numbers above 1,000. The periodic part of the pressure can lead to destabilizing moments that are controlled by a particular set of physical parameters: cylinder aspect ratio (c/a), Reynolds number (Re), coning angle (α), and coning frequency (τ). The aspect ratio is defined as the ratio of cylinder height to diameter. The Reynolds number is defined as the product of spin rate (rad/sec) and radius squared divided by the liquid kinematic viscosity. Finally, τ is defined as the ratio of coning frequency to the inertial spin frequency.

It was noted in Reference 3 that higher values of τ would be difficult to achieve for spin rates of 83.3 Hz. It was thought that an extended range for τ would eventually show a resonance similar to the high Reynolds number

condition.

Recently, increases in the range of Reynolds number and τ were made possible by using low spin rates. In this series of experiments, a large range of τ was achieved by reduction of the spin rate, yielding a maximum τ of 0.383 (a coning rate of 11.5 Hz and a spin rate of 30 Hz). Improvements in equipment reliability have led to more repeatable oscillatory pressure measurements and have allowed measurements of internal absolute pressures. On-board circuits and a twelve-channel slip ring have replaced the previous instrumentation/telemetry system (which consisted of on-board batteries, amplification and a transmitter/antenna). In this new series of tests, power to the associated circuits and transducers was passed to the rotating frame via the slip ring; hence, long run times were possible since batteries were not used (as in References 2, 3 and 5). Optical speed sensors have replaced inductive pickups to measure spin and coning frequencies.

II. EXPERIMENT DESCRIPTION AND OBSERVATIONS

The forced precession apparatus is documented in References 2 and 3 and has remained relatively unchanged. Sketches showing the cylinder, gyroscope, and coning drive are reproduced (with slight modifications where applicable) in Figures 2-4. The same cylinder and endcaps are used for these experiments. Other inserts are available and the resulting dimensions are given in TABLE 1. The lucite cylinder was refitted with drive spindles which place the geometric center of the cavity at the gimbal axis to within .01". The top cylinder endcap was fitted with two semiconductor pressure gages at positions r/a = 0.434and 0.667. Pressure gage calibrations were completed and a sample is shown in Figure 5. The two channel amplifier/filter circuit was designed and constructed to fit in the same endcap (Figure 6). A typical transfer function for the two channel circuit is shown in Figure 7. A hollow support tube allowed ribbon wire access to the slip ring assembly. The twelve-channel slip ring was mounted to the cage and rotated with the rotor assembly at the spin frequency. The slip ring allowed the transfer of power and pressure signals with approximately 0.24mV RMS noise amplitude at the spin frequency. Power channels were low-pass filtered to eliminate spin noise and stray 60 Hz. Two low voltage oscillatory signals and two low level differential DC signals were transferred from the rotating frame to the laboratory frame (Figure 6). Circuit power supply lines which provided ± 10.0 volts and a ground reference to the rotating frame are not shown for clarity.

Silicon oil with a nominal kinematic viscosity of 60,000 centistokes (cs) was used to fill the cavity. One centistoke is defined as: 1 cs = 1 cm 2 /sec $^{\sim}$ kinematic viscosity of water at standard conditions. The silicon oil viscosity and densities were measured for four temperatures:

Temp (°C)	Density (g/ml)	Viscosity (cs)
20.0	0.973	67,100
25.0	0.969	60 , 600
30.0	0.965	54,800
35.0	0.961	50,100

For the 15 degree temperature range, the density varied 1.2% and the viscosity differed 25% using the 20 degree measurements as a reference. The viscosity data were fitted using a base 10 logarithmic function (Figure 8). The cylinder was evacuated after filling to remove absorbed air. The cylinder was then sealed (at 100% fill and at 25%C). This temperature was chosen as optimum for testing purposes since it is close to normal room temperatures. The thermal expansion coefficients of the lucite cylinder, aluminum endcaps, and silicon oil are considerably different and even small room temperature changes can produce voids or overpressures in the cavity. Other oil viscosities are available in nominal values ranging from 1 to 100,000 cs. Given the constant cavity radius (a = 3.1761 cm), a set of Reynolds number ranges for various spin rates are shown in TABLE 2.

After assembly was complete, the entire rotor was dynamically balanced and placed into the cage assembly. The cage permitted precession angles (coning angle) from .5 to 3 degrees. The coning angle was calculated by measuring run-out with a dial indicator set near the cam surface. The angle is simply the arc tangent of the run-out divided by the vertical displacement of the indicator from the gimbal axes. An adjustable cam and bushing assembly holds the cage firmly in position. The coning angle is variable from 2.5 to 12 Hz. The spin drive is a DC motor capable of spin frequencies from 30 to 83.3 Hz. Varying the spin was the easiest method for producing small changes in Reynolds number.

Slow, steady spin-ups of a 100% filled cylinder produced variations in internal absolute pressures. A general decrease in absolute pressure with increasing spin was observed (TABLE 3 and Figure 9). The run time was relatively short (3 min) for the case where the spin frequency was varied from 0-80 Hz without coning motion. It was observed that the inner gage always responded with a lower absolute pressure than the outer gage. Spinning reduced the internal cylinder pressure on the endwall at these two radial positions. The absolute pressure difference between gages for any spin rate is given by:

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$$\Delta P = \frac{\rho}{2} (r_2 - r_1)(\rho)^2$$
.

A comparison between predicted pressure difference and experimental difference is also in TABLE 3. Absolute pressures were monitored continuously to remain within the gage linear response region.

The oscillatory responses of the gages were recorded, reduced, and compared with previous data. All data runs within one test set (as many as 19 runs) are for a single, constant spin rate and take approximately 20 to 30 minutes to complete. The entire system was allowed sufficient time to reach steady-state for each coning frequency according to a settling time based on the inherent viscous processes for low Reynolds numbers:

While the cylinder was spinning and coning, the internal absolute pressure would rise steadily due to viscous heating. After an extensive running

time, this heating caused the fluid to expand and pressurize (and eventually overpressurize) the gages beyond the 50 psia linear limit. The gages were not damaged since internal mechanical stops protect against overpressures to 1000 psia. No oscillating pressure signals were measured above 50 psia, and the system was allowed to cool overnight. If the room temperature was below 24°C, a vacuum bubble was observed within the cavity. Experimental runs were only started after room temperature increased so as to eliminate the vacuum bubble. (Future testing will include a temperature measurement system using thermistors to accurately monitor liquid temperatures.)

The absolute pressures measured over an extended period of time are listed in TABLE 4 and illustrated by Figure 10. The resulting history of oscillatory pressure signals remained unchanged while within the linear gage region. The internal pressure increase and the liquid temperature increase produced no change in oscillatory amplitudes. The oscillatory pressure spectra are not sensitive to small variations in liquid viscosity, density or internal cavity pressure. The liquid temperature increase over the course of this test was measured after the cylinder was quickly disassembled. The overpressure condition corresponded to a liquid temperature of 26.9°C. The change in viscosity and density with temperature, as found by fitting data, was 3.4% in viscosity and 0.16% in density. Since internal temperature was not actually monitored, experimental errors were assumed to be $\pm 1\%$ for density and $\pm 4\%$ for viscosity. All calculations involving viscosity and density use the 25° measured values.

III. DATA REDUCTION

A typical oscillatory pressure record includes responses for at least two frequencies: one is a function of the forced oscillation produced by the coning motion, while a second, and normally smaller response, occurs at the spin frequency (Figure 11). The response at the spin frequency is a residual effect resulting from a small dynamic imbalance in the system. Varying the coning rate and overlaying several spectra produces an overlay map (Figure 12). A pressure coefficient (\hat{C}_p) can be defined using the Fourier amplitude of the oscillating pressure and appropriate scale factors,

$$\hat{C}_{p} = \frac{\hat{p}_{\Upsilon}^{2}}{\alpha \rho a^{2} p^{2}} \tag{2}$$

where

is the oscillating pressure peak amplitude

 α is the precession angle

 ρ is the fluid density

a is the cylinder radius

p is the cylinder inertial spin rate

$$\hat{Y}$$
 is $\frac{\tau}{|\tau|}$

Prograde precession is established when both the precession and spin vectors rotate in the same direction. Retrograde precession is defined when spin and coning have opposite senses of rotation. Response plots show the pressure coefficient versus τ . \hat{C}_p and τ are sensitive to the relative rotation sense of the spin and precession. Hence, \hat{C}_p and τ are positive for prograde motion and both negative for retrograde motion. A tabulation of all oscillating pressure measurements and coefficient calculations are given for each set of experiments.

Prior to the first data runs, gyroscope system errors based on instrument and apparatus capabilities were determined. These are listed in TABLE 5. The plotted data include error bars as a measure of the total system error. The maximum and minimum $\hat{\mathsf{C}}_p$ values are calculated from the error parameters. For example, maximum values are simply the result of calculating $\hat{\mathsf{C}}_p$ with the largest pressure (pressure plus pressure error) divided by the smallest scale factors (factor minus factor error). Error calculations in pressure coefficients are tabulated as minimum and maximum values. These values are shown as the vertical range of error bars. τ errors are represented by the horizontal span of error caps. Error bars are omitted on some graphs for clarity.

The first experiments were performed at a Reynolds number of 8.7. The coning angle was set at 40 mils (2.25°) using a gunner's quadrant. This method proved ineffective for smaller angles with a measurement error of 0.5 mil. Thus, smaller angles were set using a dial indicator. The data were taken for prograde motion at 10 intervals of increasing coning rate. Additional measurements were taken as the coning speed was reduced to the slowest rate. The results are tabulated in TABLES 6a and 6b. \hat{C}_p values for the two transducer positions are plotted in Figure 13. Throughout all of the tests, \hat{C}_p values for r/a=0.667 always produced larger pressure coefficient values than r/a=0.434. This test verified the preliminary findings of Reference 3 where pressure varied nearly linearly with increasing nondimensional coning frequency (τ) .

A minor modification to Reference 3 data included more exact density and viscosity measurements extracted from Reference 6. One more test was performed at this Reynolds number of 8.7. Sets of data are included as TABLES 9a and 9b. The data were taken for prograde and retrograde motion transducer position = 0.667. A plot of both prograde and retrograde data (TABLES 7a and 7b) with modified Reference 3 data depicts the small differences between the data (Figure 14). Differences in gyroscope apparatus, liquids used, and data collection account for the data discrepancies. The new data encompass nearly all the Reference 3 data within the $\hat{\mathbb{C}}_p$ error range. Considering the change in apparatus (see References 2 and 3), it can be stated that the replication of previous results has been accomplished.

The next area of experimentation was the verification of linear theory applications (linear with coning angle) for low Reynolds numbers. At sufficiently large coning angles and for high Reynolds number, the pressure

coefficient data showed nonlinear (not linear in coning angle) and even aperiodic responses for prograde motion. Figure 15 is reproduced from Reference 2. For a Reynolds number of 80,000, the nonlinearities first occur at a coning angle of 0.22 degrees. Vertical lines connecting two points represent the aperiodic fluctuations in pressure. They are not representative of system errors. Figure 15 data also shows frequency shifts for the nonlinear data. For lower Reynolds numbers (as low as 10,000), Whiting found the nonlinearities to occur at a higher coning angle. 2

A set of experiments were conducted at the coning angles of 0.5, 1 and 2. The coning cam bushing was replaced by a thin set of roller bearings and the coning angle was limited to a maximum of two degrees. Future testing will include a new cam design using roller bearings. The spin rate was lowered to 70.0 Hz to extend roll bearing life. The experiments were run in much the same fashion as previous tests. Nineteen runs were completed at each angle for both prograde and retrograde motions and both transducer positions. The final data are tabulated for coning angle = 0.5 degrees in TABLES 8a-b. Likewise, data for a coning angle of 1.0 degree are listed in TABLES 9a-b. TABLES 10a-b are arranged similarly for a coning angle of 2.0 degrees. Re = 7.3 data are plotted in Figure 16 where prograde and retrograde are shown for the radial position = 0.667. The 0.5 degree data differ considerably due to the small coning angle and low signal levels. When viewed on this scale the data do not show the nonlinear trends evidenced by Whiting at higher Reynolds numbers.

Another aim of the experimental work was to investigate extending the range of τ by simply decreasing the spin rate. For the same range in coning rates, an extended range of τ results. A change in spin also affects a change in Reynolds number. Reynolds number 3.1 is the result of a spin rate of 30 Hz and a τ ranging from -0.383 to 0.383. The Reynolds number 8.7 is attained at a spin rate of 83.3 Hz and τ ranges from -0.138 to 0.138. The relative extension in τ for lower spin rates is evident from a comparison of Reynolds number 3.1 - 8.7 is shown in Figure 17. Larger errors in amplifier gain occur due to the high pass filtering characteristics and low spin rates. Several tests were run at medium spin rates of 50.0 Hz and 30 Hz. Measurements were taken for prograde and retrograde motions for r/a = 0.667. TABLES 11a and 11b list data for Reynolds number 5.2 (Figure 18). TABLES 12a and 12b give data for Reynolds number 3.1 (Figure 19). The experimental C_{D} data for Reynolds number 3.1 seem to have a nonlinear dependence upon τ , resembling the leading edge of a resonant response curve.

An example of two theories which are applicable at low Reynolds number are the spatial eigenvalue method and the University of Wisconsin's finite difference method. These codes are available at BRL.

The spatial eigenvalue method developed by Hall, Sedney and Gerber reduces the incompressible Navier-Stokes equations to a set of linear partial differential equations. The angle of coning motion is assumed small. A particular solution is employed that satisfies the axial and lateral cylinder wall boundary conditions. The flow variables are expressed as eigenfunction expansions with the coefficients determined by satisfying the cylinder endwall boundary conditions; a least squares method has been used for this purpose. The method runs very efficiently (less than 10 cpu seconds) on a VAX 8600

mini-computer for low Reynolds numbers (< 100) with small increases in computer run time for larger Reynolds number values up to 2000.

University of Wisconsin's computation solves the steady state, incompressible Navier-Stokes equations, including non-linear effects, for a precessing/spinning cylinder at a fixed precession angle. The code uses an iterative finite-difference method based on modified line successive-over-relaxation and a pressure update from the gradient of the velocity field. Nusca 12 has shown that the code runs efficiently: (less than 1 cpu hour) on a VAX 8600 mini-computer for low Reynolds numbers (< 80) but requires the use of a CRAY XMP computer for larger Reynolds number values up to 300.

Comparisons of experiment to the two theories are given in Figures 20 and 21 and TABLES 13 and 14. These theories aid in examining trends and extrapolation past experiment capabilities.

IV. CONCLUSIONS

A small gyroscope fixture was used to carry a liquid-filled cylinder at relatively low spin and coning rates. The experiments were conducted under controlled, repeatable conditions. The purpose of the experiments was to provide a basis for full-scale simulations of liquid payloads. Based on these preliminary results, extensive testing can be accomplished on the BRL Flight Simulator using a full-scale cylinder and larger instrumentation payload capacity.

Oscillatory and absolute pressure data were obtained for a relatively low Reynolds number range. Testing included establishing instrumentation reliability, repeating previously published low Reynolds number data, expanding the range in nondimensional coning frequency and Reynolds number, and providing a data base for comparisons with current linear theory applications at low Reynolds number.

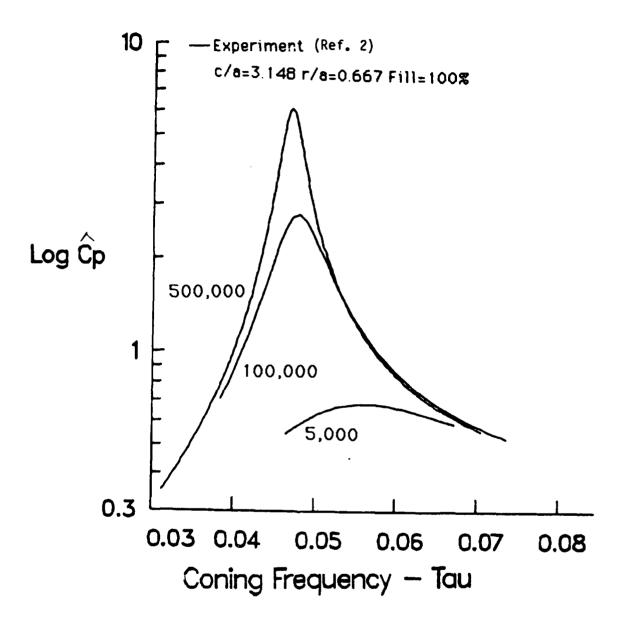


Figure 1. Cubic spline fit to experimental data for various high Reynolds number cases (Ref. 2).

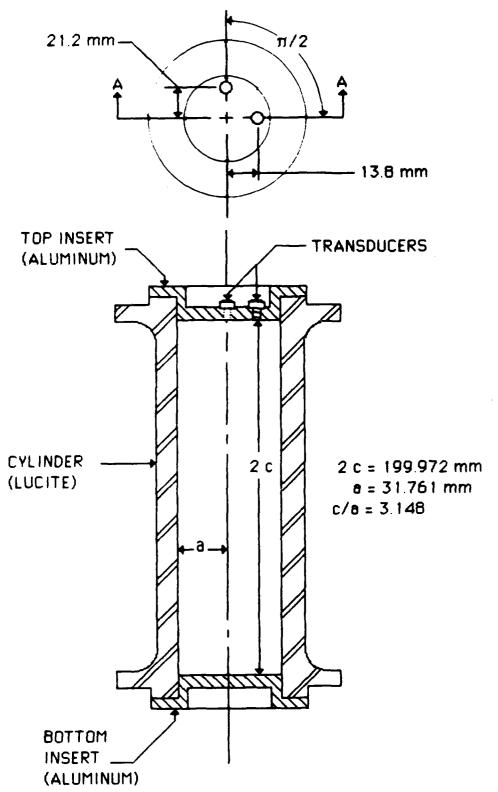


Figure 2. Cylinder dimensions and transducer locations.

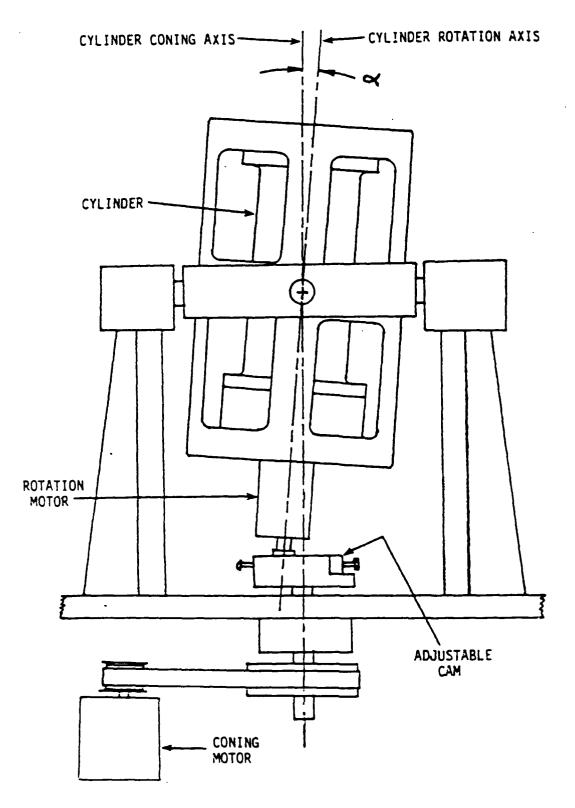


Figure 3. Forced precession gyroscope apparatus.

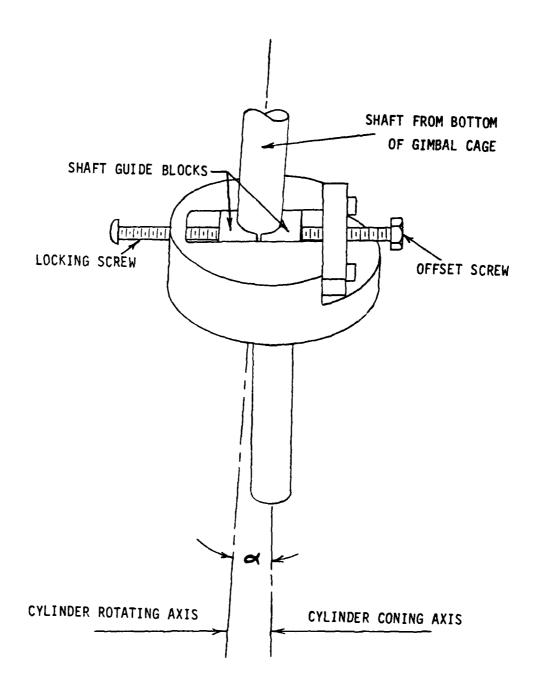


Figure 4. Precession angle adjustment cam.

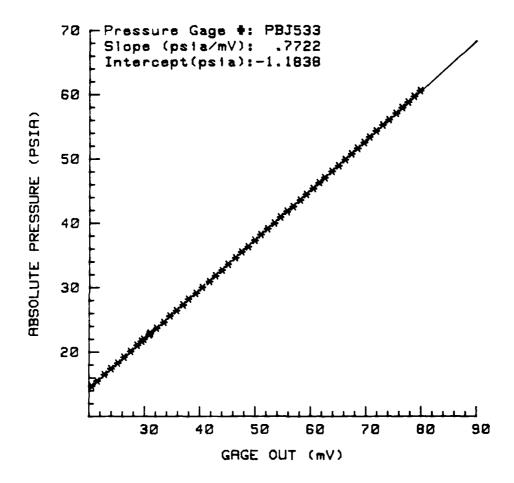


Figure 5. Pressure gage calibration for r/a = 0.667.

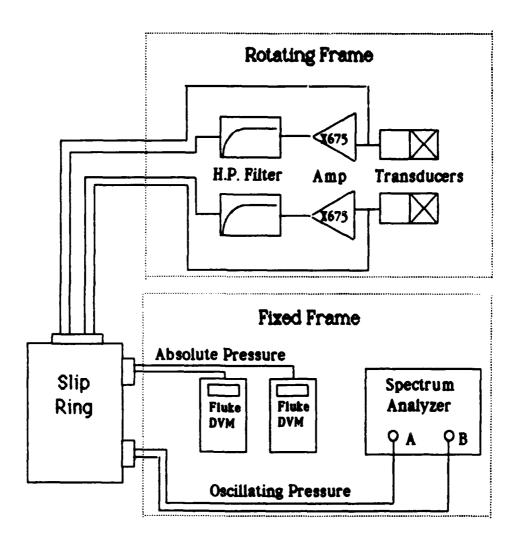


Figure 6. Instrumentation schematic.

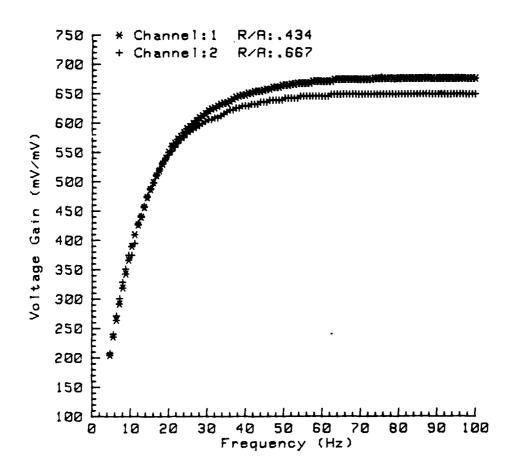


Figure 7. High pass filter amplifier transfer function.

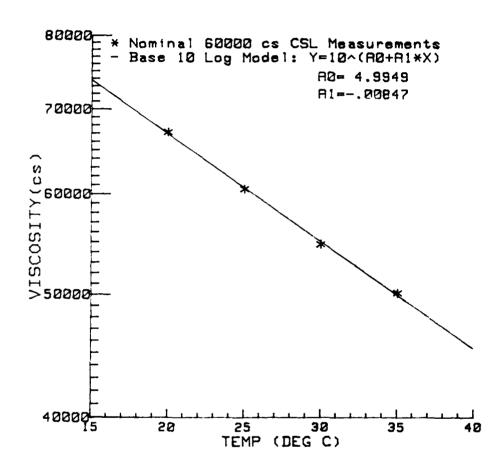


Figure 8. Liquid viscosity measurements and logarithmic function fit.

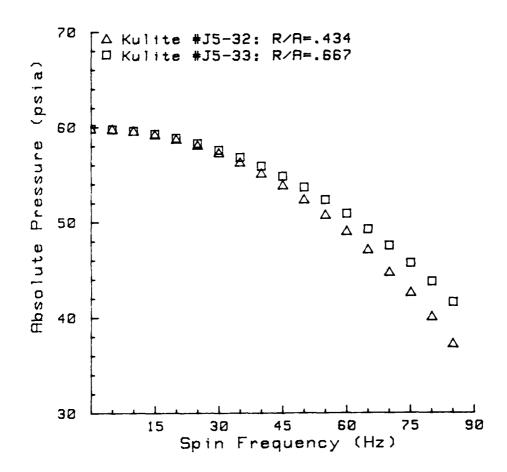


Figure 9. Absolute pressure decrease on an end wall for a slow spin-up.

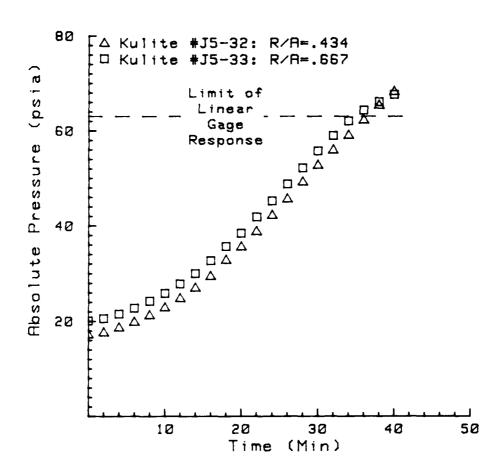


Figure 10. Absolute pressure rise for extended running time, (coning rate = 5 Hz, spin rate = 70 Hz).

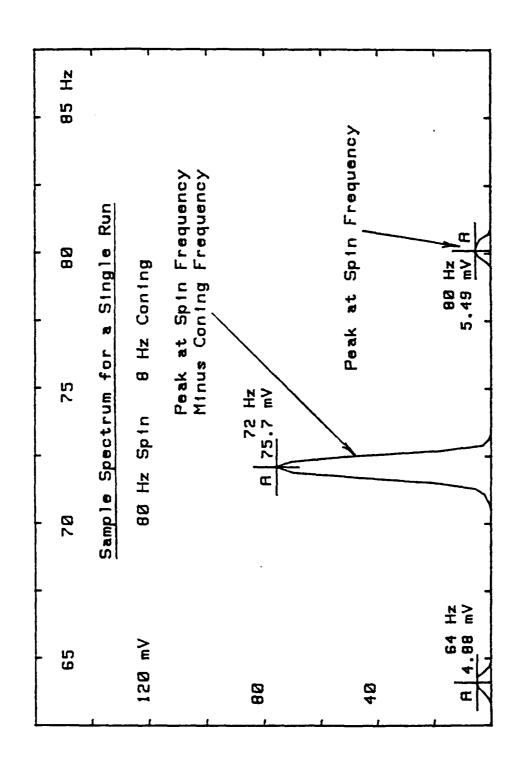
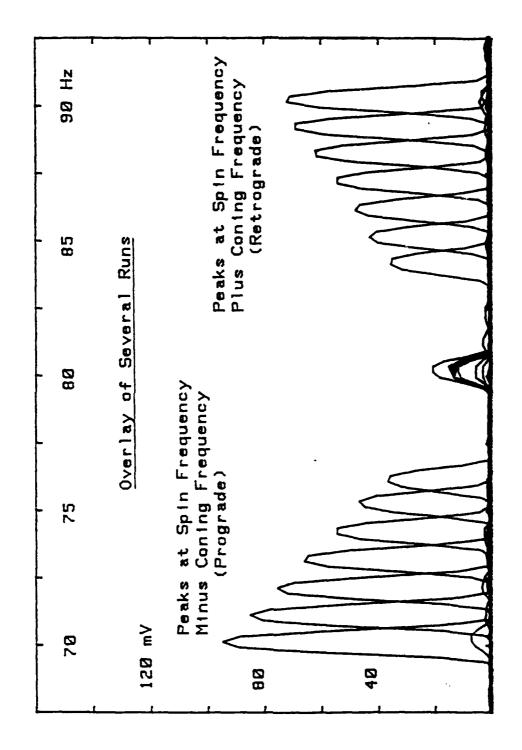


Figure 11. Spectral response for oscillatory pressures.



and the second of the second o

Figure 12. Spectra of several runs overlayed for low Reynolds number.

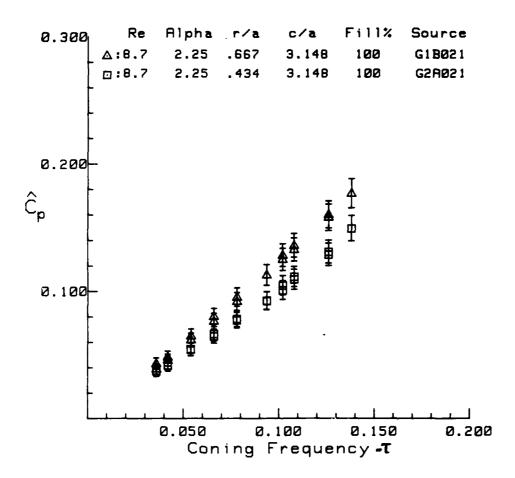


Figure 13. Prograde pressure coefficient data for two radial positions $(r/a = 0.434 \text{ and } 0.667 \text{ at Re near } 8.8, \alpha = 2.25^{\circ}).$

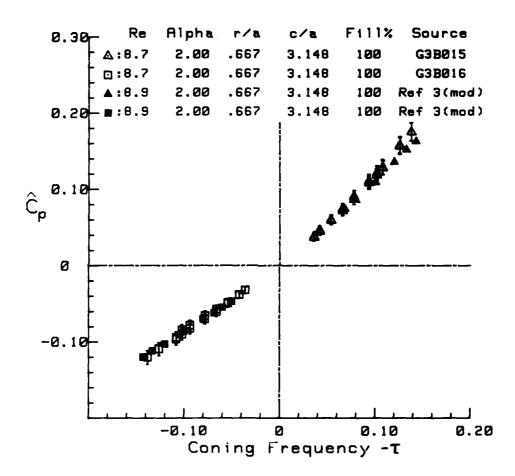
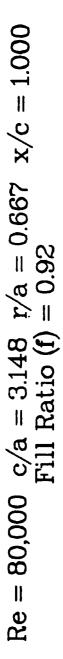


Figure 14. Prograde and retrograde pressure coefficient comparison with modified Ref. 3 data for Re near 8.8, α = 2.00°, r/a = 0.667.



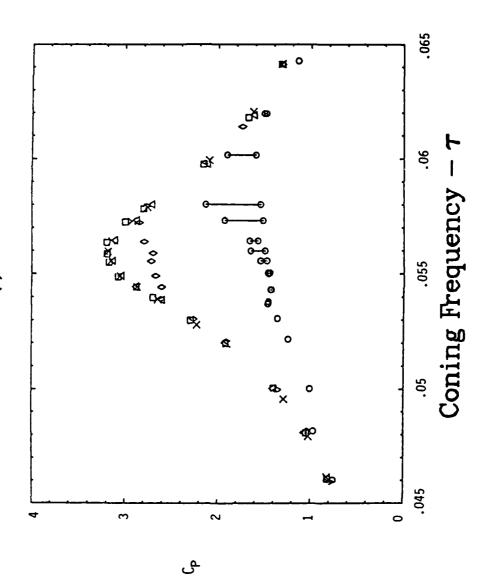


Figure 15. Experimental prograde data (f = .92), Δ = 0.022°, Ω = 0.051°, x = 0.105°, ϕ = 0.22°, o = 0.50° (Ref. 2).

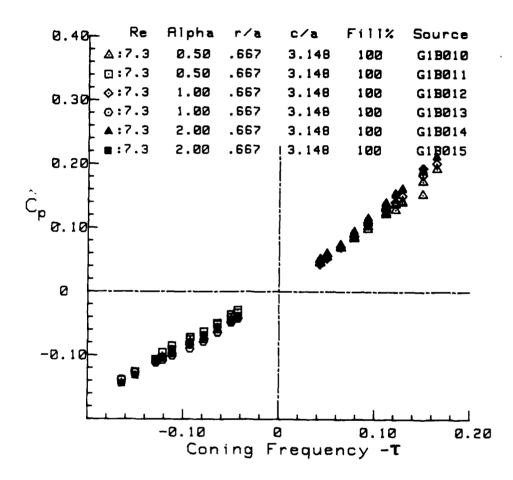


Figure 16. Prograde and retrograde pressure coefficient comparison for linearity with coning angle, Re = 7.3, α = 0.5, 1 and 2 deg, r/a = 0.667.

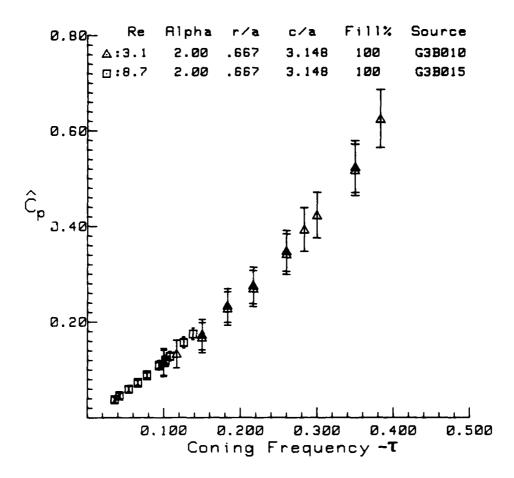


Figure 17. Expanded coning frequency and error ranges due to low spin rates.

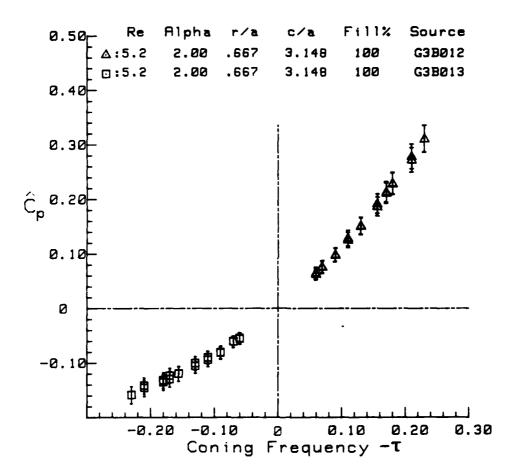


Figure 18. Prograde and retrograde pressure coefficient data for Re = 5.2, α = 2.00° , r/a = 0.667.

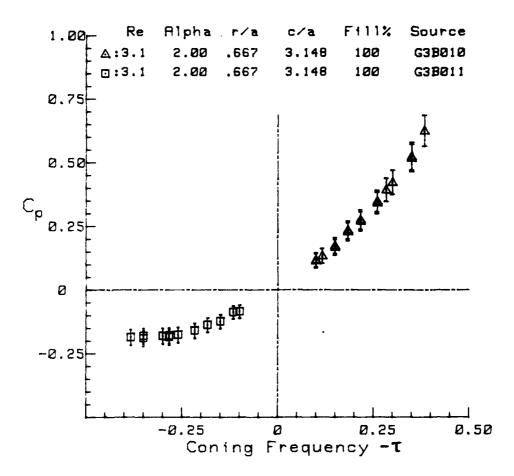
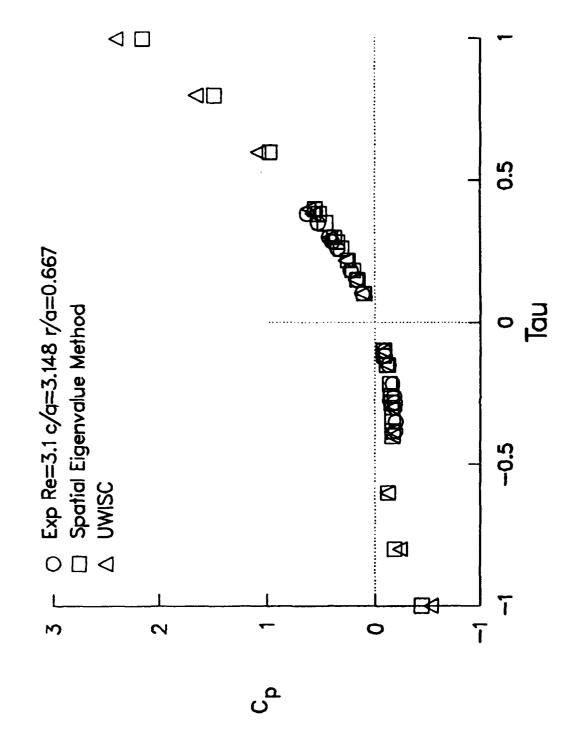


Figure 19. Prograde and retrograde pressure coefficient data for Re = 3.1, α = 2.00°, r/a = 0.667.



Comparison of experimental data to two available low Reynolds number theories for Re = 3.1.

Figure 20.

27

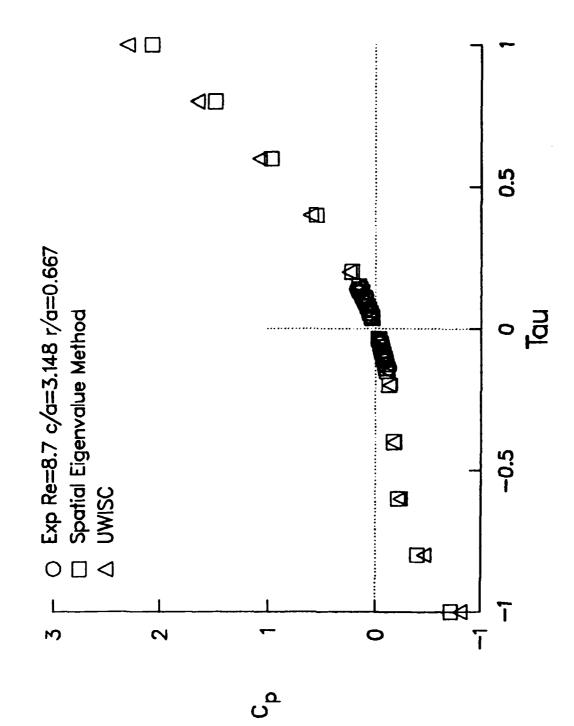


Figure 21. Comparison of experimental data to two available low Reynolds number theories for Re=8.7.

TABLE 1. Cavity Dimensions of Lucite Cylinder with Various Inserts

	c (cm)	a (cm)	c/a	Volume (cc)
Insert #1				
Maximum	3.1838	3.1780	1.0028	202.04
Minimum	3.1802	3.1747	1.0007	201.40
Mean	3.1819	3.1761	1.0018	201.68
Insert #2				·
Maximum	3.3395	3.1780	1.0519	211.92
Minimum	3.3365	3.1747	1.0499	211.30
Mean	3.3378	3.1761	1.0509	211.56
Insert #3				
Maximum	8.1949	3.1780	2.5813	520.05
Minimum	8.1923	3.1747	2.5778	518.80
Mean	8.1935	3.1761	2.5797	519.34
Insert #4				
Maximum	8.9578	3.1780	2.8216	568.46
Minimum	8.9521	3.1747	2.8169	566.92
Mean	8.9550	3.1761	2.8195	567.61
Insert #5				·····
Maximum	9.5292	3.1780	3.0016	604.72
Minimum	9.5259	3.1747	2.9974	603.26
Mean	9.5274	3.1761	2.9997	603.89
Insert #6				
Maximum	10.0000	3.1780	3.1499	634.60
Minimum	9.9972	3.1747	3.1457	633.10
Mean	9.9986	3.1761	3.1480	633.75

Reynolds Number Calculations for Available Spin Rates and Actual Liquid Viscosities for an Internal Cylinder Radius of 3.176 cm TABLE 2.

			Reyr	Reynolds Number	er		
20.0	1.21E+05	1.28E+03	2.42E+02	1.26E+02	13.0	2.09	1.31
30.0	1.81E+05	1.92E+03	3.62E+02	1.88E+02	19.6	3.14	1.97
40.0	2.41E+05	2.56E+03	4.83E+02	2.51E+02	26.1	4.19	2.62
Spin (Hz) 50.0	3.02E+05	3.19E+03	6.04E+02	3.14E+02	32.6	5.23	3.28
0.09	3.62E+05	3.83E+03	7.25E+02	3.77E+02	39.1	6.28	3.94
70.0	4.23E+05	4.47E+03	8.45E+02	4.40E+02	45.6	7.33	4.59
80.0	4.83E+05	5.11E+03	9.66E+02	5.03E+02	52.2	8.37	5.25
83.3	5.03E+05	5.32E+03	1.01E+03	5.23E+02	54.3	8.72	5.47
Actual 25° C	1.05	99.2	524.8	1009	9720	60550	96590
Nom Visc (cs)	1	100	200	18	10k	60k	100k

TABLE 3. Absolute Pressure Measurements and Predicted Pressure Differences for Constant spin rates.

Al	BSOLUTE P	ressure M	EASUREM	ENTS
Coning	(Hz)= 0	specif	ic gravity:	=0.969
Spin	r=1.38 cm	r=2.12 cm	Ехр	Predicted
Rate	Pressure	Pressure	Δp	Δp
(Hz)	(psia)	(psia)	(psi)	(psi)
0	59.7	59.8	0.1	0.0
5	59.7	59.7	0.0	0.0
10	59.5	59.6	0.1	0.1
15	59.1	59.3	0.2	0.2
20	58.6	58.8	0.2	0.3
25	58.0	58.3	0.3	0.4
30	57.2	57.6	0.4	0.6
35	56.2	56.8	0.6	0.9
40	55.0	55.9	0.9	1.1
45	53.8	54.8	1.0	1.5
50	52.3	53.6	1.3	1.8
55	50.7	52.3	1.6	2.2
60	48.9	50.9	2.0	2.6
65	47.0	49.2	2.2	3.0
70	44.6	47.5	2.9	3.5
75	42.5	45.7	3.2	4.0
80	40.0	43.8	3.8	4.6
85	37.1	41.6	4.5	5.2

TABLE 4. Absolute Pressure Measurements for Constant Spin $(70~{\rm Hz})$ and Coning Motion $(5~{\rm Hz})$

<u> </u>	RBSOLUTE	PRESSURE MEASUREM	ENTS RE:	7.3
SPIN(H		NING(Hz):5 C/		VISC(cs):60000
TIME	KUJ532	R. A: .434	KUJ533	R/A:.667
(min)	Voltage(mV)	Pressure(psia)	Voltage(mV)	Pressure (psia)
0	19.8	17.1	27.5	20.1
2	20.4	17.6	28.2	20.6
4	21.7	18.6	29.4	21.5
6	23.2	19.7	31.0	22.8
8	25.0	21.1	32.9	24.2
10	27.1	22.8	35.0	25.8
12	29.6	24.7	37.6	27.9
14	32.4	26.9	40.4	30.0
16	35.5	29.3	43.8	32.6
18	39.8	32.7	47.7	35.6
20	43.4	35.5	51.3	38.4
55	47.5	38.7	55.7	41.8
24	51.9	42.1	60.1	45.2
26	56.3	45.6	64.7	48.8
28	60.9	49.1	69.1	52.2
30	65.4	52.7	73.7	55.7
32	69.5	55.8	77.9	59.0
34	73.5	59.0	81.9	62.1
36	77.6	62.2	84.8	64.3
38	81.6	65.3	87.1	66.1
40	85.3	68.2	89.1	67.6

TABLE 5. Forced Precession Gyroscope System Errors

FORCED PRECE	ESSION GYROSCOPE	SYSTEM ERRORS
Parameter	Range	Error
Coning Rate	25-12 Hz	+/- 0.1 Hz
Spin Rate	30.0-83.3 Hz	+/- 0.15 Hz
Cylinder Radius	3.1761 cm	+/- 0.0012 cm
Cytinder 1/2 Ht	9.9986 cm	+/- 0.0014 cm
Fluid Viscosity	60600 cs	+/- 40%
Fluid Density	0.969g/cc	+/- 1.0%
Coning Angle	.5/1/2deg	+/- 0.021 deg
Pressure Signal	10.0-145 mV rms	+/- 20 mV rms
Signal Gain	450-675	+/- 2%
Pressure cal	0.7798/.7722 psi/mV	+/- 0.2%
Pressure Incpt	1.652/-1.184 psia	+/- 2.0%

TABLE 6a. Prograde Oscillatory Pressure Data for Re = 8.7, α = 2.25°, r/a = 0.667

):100):21.2 m:2 :8.7	0.0048 0.0048 0.0053 0.103 0.121 0.142 0.134 0.0099	• 04
l Ratio(% ition (mm nnl Id Nu nolds Num	© D 0.0043 0.0043 0.0055 0.113 0.1138 0.0132 0.0052	25
.148 Fil 1838 Pos 2.25 Cha .969 Rey 10.0	0.0039 0.0039 0.0039 0.0039 0.1130 0.124 0.1165 0.0035 0.0035	٠ 5
t Rat(C/A):3, cpt(psi):-1, ng Ang(deg): ity(gm/cc): volt(v DC):	នេល।೦೧೯೯೭೦೦★COC೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯೯	· ner+n
3 Aspo 2 Intr 7 Coni K Dens Gage	VO VO Garina Gar	4
Freq(Hz): 83. (psi/mV):.772 ad (R/A): .66 sity(cs): 60 n:Prograde	Amplitude (Volts rms) 0.0389 0.0389 0.0436 0.0586 0.0726 0.1020 0.1160 0.1450 0.1450 0.1430 0.1200 0.1200 0.1200 0.0831 0.0692	. 035
Spin F Slope (Pos/Re Viscos Motior	Tau 0.0036 0.036 0.0036 0.0038 0.126 0.126 0.002 0.002 0.002 0.002 0.002	
Name:G1B021 ID Num: 33 s (mm):31.8 deg C):25.0 ype: Lucite	Coning Rate (Hz) 3.00 3.00 4.50 6.50 9.00 11.50 11.50 7.80 8.50 9.00 8.50 9.00 8.50 9.00	•
File Gage Radiu Room(Run 1 1 2 2 4 3 6 7 6 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	

TABLE 6b. Prograde Oscillatory Pressure Data for Re = 8.7, α = 2.25° , r/a = 0.434

%):100 um):13.8 lum:1 im:8.7	¥ O	.04	0.040	.07	.08	.10	.11	. 12	.14	.15	.13	.11	. 10	.10	.08	.07	.05	.04	.04
l Ratio(ition (π nnl Id N nolds Nu	رن م	E	0.041	90.	.03	.09	.10	.11	.13	. 14	. 12	. 10	. 10	.09	.0	• 06	.05	4	'n
.148 Fil 6518 Pos: 2.25 Cha .969 Rey 10.0	OM Op	•	0.050	• 06	.07	.08	• 09	.10	.12	.13	. 12	. 10	• 00	.08	.03	.05	.04	.03	.03
<pre>Rat(C/A):3 pt(psi): 1. I Ang (deg): Y(gm/cc): Yolt(V DC):</pre>	Pressure Dynes/cm^2	. 87 E+	4.33E+03 5.72E+03	.97 E+0	.21E+0	.69E+0	.10E+0	.17E+0	.37 E+0	.56E+0	.35E+0	.15E+0	.06E+0	.7 1E+0	.09E+0	.7 8E+0	.68E+0	.39E+0	.92E+0
3 Aspet 8 Intrep 4 Coning K Densit Gage V	Voltage Gain																		
Freq(Hz): 83. (psi/mV):.779 ad (R/A): .43 sity(cs): 60 n:Prograde	Amplitude (Volts rms)	•	020	.062	.073	.086	.097	.104	.122	.139	.120	.102	. 094	.086	.072	.060	.050	.039	.034
Spin I Slope Pos/Ra Viscos Motior	Tau	0.036	.05	• 06	.07	• 09	. 10	. 10	. 12	. 13	. 12	. 10	. 10	• 09	.07	• 06	.05	.04	• 03
Name: G2A021 ID Num: 32 S (mm): 31.8 deg C): 25.0 ype: Lucite	Coning Rate (Hz)	0.	4.50	3	.5	8	٠,	0.	0.5	Š	0.5	0	٠.	φ.	. 5	٠ ک	.5	.5	0.
File Gage Radiu Room(Cyl T	Run	ч с	4 W	4	'n	9	7	œ	σ	10									

 $\alpha = 2.00^{\circ}$, r/a = 0.667= 8.7, Prograde Oscillatory Pressure Data for Re TABLE 7a.

):100):21.2 m:2 :8.7	Σ(Ω α α γ		90.	.08	.09	. 12	.13	.13	.16	. 18	• 16	.13	. 12	.11	•00	.07	90.	.05	.04
l Ratio(%) ition (mm) nnl Id Nur nolds Num:	ڻ م	0	90.	.07	• 09	11:	. 12	. 12	. 15	. 17	. 15	. 12	7	. 10	.08	.07	.05	.04	• 03
.148 Fil 1838 Pos 2.00 Cha .969 Rey 10.0	Agin Op	0.034	.05	• 06	.08	.10	.11	.12	.14	.16	. 14	.11	11.	.10	80.	90.	.05	.04	.03
cpt(psi):-1. ng Ang(deg): ity(gm/cc): Volt(V DC):	Pressure Dynes/cm^2	57E+	.62E+0	.96E+0	.44E+0	.04E+0	.13E+0	.20E+0	.47E+0	.63E+0	.46E+0	.19E+0	.10E+0	.01E+0	.09E+0	.68E+0	.51E+0	.17E+0	E+0
3 Aspet 2 Intro 7 Conin K Densi Gage	Voltage Gain	649	, 4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
Freq(Hz): 83. (psi/mV):.772 ad (R/A): .66 sity(cs): 60 n:Prograde	Amplitude (Volts rms)	0.0308	.048	.060	.072	.089	. 097	.104	.127	.141	.126	.103	.095	.087	.069	.057	.047	.036	29
Spin R Slope(Pos/Ra Viscos	Tau	•	05	• 06	.07	.09	.10	. 10	. 12	13	. 12	. 10	. 10	.09	.07	• 06	.05	.04	03
Name: G3B015 ID Num: 33 IS (mm): 31.8 deg C): 25.0	Coning Rate (Hz)	3.00		.5	3	ω.	.5	0.	.5	11.50	ς.	0.	8.50	8	٠.	5	.5	5	0.
File N Gage II Radius Room(d	Run	٦,	4 m	4	ഗ	9	7	œ	σ	10	11	12						18	

TABLE 7b. Retrograde Oscillatory Pressure Data for Re = 8.7, α = 2.00° , r/a = 0.667

o(%):100 (mm):21.2 Num:2 Num:8.7	(2) (2) (3) (4) (4) (4) (4) (4) (4) (4) (4) (4) (4	.02	.03	• 0 •	.05	90.	70.	φ Ο α	ָ כפי פי	3 -	-0.101	.08	.07	.07	90.	.05	.04	.03	0.02
ll Ratio(%):10 sition (mm):21 annl Id Num:2 ynolds Num:8.7	ئ م	0.	0.	0	0,0				? ~	-	-0.109	0	0	0	0	0	0	0	-0.032
.148 Fi 1838 Po 2.00 Ch .969 Re 10.0	Aπi Oπi Oπi Oπi Oπi Oπi Oπi Oπi Oπi Oπi O	.03	.04	.05	0.06	.07	2,5	5.5	֓֡֓֞֝֟֓֓֓֓֟֝֓֓֓֓֓֓֟֝֓֓֓֟֓֓֓֓֓֓֡֓֓֡֓֓֓֡֓֡֓֡֓֡		-0.118	.10	60.	80.	.07	90.	.05	.04	-0.037
<pre>rct Rat(C/A):3 rcpt(psi):-1: ing Ang(deg): sity(gm/cc): le Volt(V DC):</pre>	Pressure Dynes/cm^2	.00E+0	_	.63E+0	.69E+0	.54E+0	./UE+U	.41E+U	07540	12E+0	1.02E+04	.80E+0	. 87 E+0	.28E+0	.11E+0	.34E+0	.53E+0	.57E+0	.00E+0
.3 Aspect 22 Intro 67 Conir 0K Densi Gage	Voltage Gain	4	4	4	4.	4.	4.	4	4 4	* 4	649	4	4	4	4	4	4	4	4
Freq(Hz): 83 (psi/mV):.77 ad (R/A): .6 sity(cs): 6 n:Retrograde	Amplitude (Volts rms)	.025	.030	.040	.049	.056	90.	2.70.	/ 00	200	0.0879	.076	.068	.062	.052	.046	.039	.030	. 025
Spin Slope Pos/R Visco Motio	Tau	•	.04	.05	.06	.07	5.5	01.). 13	77.	-0.126	.10	.10	.09	.07	• 06	.05	.04	.03
Name: G3B016 ID Num: 33 s (mm): 31.8 deg C): 25.0 ype: Lucite	Coning Rate (Hz)	0.	•	•	-5.50	٠,	:		٠ ٧ د	· -	10.	-9.00	•	•	•	-5.50	•	-3.50	•
File Nage II Gage II Radius Room(de	Run		7	m ·	4 7 ≀	ın v	ء م	~ °	o c	۷ د	11	12		14	15	16	11	18	19

TABLE 8a. Prograde Oscillatory Pressure Data for Re = 7.3, α = 0.50°, r/a = 0.667

):3.148 Fill Ratio(%):100	Slope(psi/mV):.7722 Intrcpt(psi):-1.1838 Position (mm):21.2	g): .50 Channl Id Num:2	:): .969 Reynolds Num:7.3	C):10.0
Aspct Rat(C/A	Intrcpt(psi):-1.1838	Coning Ang (de		Gage Volt(V DC):10.0
Spin Freg(Hz): 70.0	Slope(psi/mV):.7722	Pos/Rad (R/A): .667	Viscosity(cs): 60K	Motion:Prograde
File Name:G1B010	Gage ID Num: 33	Radius (mm):31.8	Room (deg C): 25.0	Cyl Type: Lucite

Σ (Ω α α x	10	0.074	0.	7	ι.	7	7		7	7	٦.	Τ.	7	٦.	٦.	٦.	0	0	•
လ ရ	0.047	.05	0.070	9	. 10	12	.13	.14	. 17	. 19	. 15	. 14	. 12	. 12	9	.08	.06	0.060	.04
Min Cp	0.030	0	0	9	٠,	7	7	7	7		٦.	٦.	7	0	•	9	0	•	•
Pressure Dynes/cm^2	E+0	94E+	.15E+0	.41E+0	.69E+0	.05E+0	. 26	.34E+0	.85E+0	3.18E+03	.51E+0	.30E+0	.12E+0	.01E+0	.62E+	E+0	.14E+0	9.83E+02	.49E+0
Voltage Gain	649	649	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	649	4
Amplitude (Volts rms)	90		600	.012	.014	.017	.019	020	.024	.027	.021	.019	.018	.017	14	.011	.009	.00	0.0065
Tau	0.043	•	0	0	•	7	_	7	٦.	0.164	٦.	7	٦.	7	•	•	0.	0.050	۰.
Coning Rate (Hz)	3.00	3.50	4.50	5.50	6.50	7.80	8.50	•	10.50	•	10.50	9.00	8.50	7.80	6.50	.5	4.50	3.50	3.00
Run	, !	7	m	4	S	9	٢	Φ	6	10	11	12	13	14	15	16	17	18	19

TABLE 8b. Retrograde Oscillatory Pressure Data for Re = 7.3, α = 0.50°, r/a = 0.667

8):100 m):21.2 lum:2 n:7.3	CO C	.01
ill Ratio(% osition (mm hannl Id Nu eynolds Num	0.00 0.00 0.00 0.00 0.00 0.00 0.126 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.	-0.029
.148 F 1838 P .50 C	Cain 0.0059 0.0052 0.0052 0.0053 0.0053 0.0053 0.0053	
<pre>cct Rat(C/A):3 :rcpt(psi):-1. ning Ang(deg): nsity(gm/cc): je Volt(V DC):</pre>	8 8 1 8 8 8 4 4 1 1 6 7 8 7 8 4 8 8 8 1 8 8 8 4 4 1 1 6 7 8 7 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	.81E+0
0 Asg 2 Int 7 Cor K Der Gae	OO CO C	r 4
Freq(Hz): 70. (psi/mV):.772 ad (R/A): .66 sity(cs): 60 n:Retrograde	Amplitude (Volts rms) 0.0047 0.0057 0.0057 0.0130 0.0148 0.0152 0.0179 0.0179 0.0152 0.0121 0.0121	.004
Spin Slope Pos/R Visco	Tau -0.043 -0.050 -0.079 -0.121 -0.129 -0.129 -0.093	40.0
Name:G1B011 ID Num: 33 IS (mm):31.8 deg C):25.0	Hz) (Hz) (Hz) (Hz) (Hz) (Hz) (Hz) (Hz) (3.00
File Gage Radius Room(CY1 Ty	Run 1 1 2 6 8 4 3 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	

TABLE 9a. Prograde Oscillatory Pressure Data for Re = 7.3, α = 1.00°, r/a = 0.667

Σ: ⟨Ω α σ ×	1 1 1	.05	• 06	.08	0.101	.12	.14	.15	.16	.21	.22	.20	91.	.15	.14	.11	.10	.08	.06	. 05
ڻ م	1 1 1	.04	.05	.07	0.088	.10	.13	. 14	.15	. 19	. 20	. 18	. 15	.14	. 12	. 10	.08	.07	.05	.04
æ Ogi n	f	.03	.04	.05	0.076	• 09	.11	. 12	.13	.17	. 18	• 16	.13	. 12	.11	σ	.07	.05	.04	\sim
Pressure Dynes/cm^2		.55E+0	.85E+0	.30E+0	2.89E+03	.57E+0	.31E+0	.64E+0	. 97 E+0	0E+0	.65E+0	.04E+0	.97 E+0	.64E+0	.21E+0	.45E+0	.85E+0	.30E+0	.7 1E+0	2E+0
Voltage Gain	!!!	4	4	4	649	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
Amplitude (Volts rms)	!!!!!!	.013	.016	.019	0.0250	.030	.037	.039	.042	.055	.057	.051	.042	.039	.036	.029	.024	.019	.014	.012
Tau		.04	.05	• 06	0.079	• 09	.11	. 12	. 12	.15	. 16	.15	. 12	. 12	.11	. 09	.03	• 06	.05	.04
Coning Rate (Hz)		3.00	3.50	4.50	5.50	6.50	7.80	8.50	•	0	•	0	•	•	•	6.50	5.50	4.50	3.50	3.00
Run	!	-	7	က	4	ß	9	7	۵	6	10	11	12	13		15			18	19

TABLE 9b. Retrograde Oscillatory Pressure Data for Re = 7.3, α = 1.00°, r/a = 0.667

(8):100 imm):21.2 Num:2 ium:7.3	CAR A CO	•
l Ratio ition (nnl Id nolds N	0.043 0.043 0.064 0.103 0.103 0.097 0.093	•
.148 Fil 1838 Pos 1.00 Cha .969 Rey 10.0	CAS O CO C	•
: Rat(C/A):3 :pt(psi):-1. ig Ang(deg): .ty(gm/cc): .volt(V DC):	Pressure Dynes/cm ² 2 1.35E+03 1.60E+03 2.12E+03 2.12E+03 2.94E+03 3.31E+03 3.58E+03 3.58E+03 3.58E+03 3.58E+03 3.58E+03 3.58E+03 3.58E+03 4.15E+03 4.15E+03 2.75E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03 3.66E+03	}
.0 Aspet 22 Intrc 67 Conin 0K Densi Gage	O O O O O O O O O O O O O O O O O O O	•
Freq(Hz): 70. (psi/mV): 772 (ad (R/A): .66 (sity(cs): 60 n:Retrograde	Amplitude (Volts rms) 0.0117 0.0138 0.0183 0.0254 0.0254 0.0309 0.0309 0.0318 0.0391 0.0391 0.0391 0.0294 0.0276 0.0236	1 1 2
Spin I Slope Pos/Ra Viscos Motion	Tau -0.043 -0.050 -0.050 -0.0130 -0.121 -0.129 -0.093 -0.079	•
Name:GlB013 ID Num: 33 us (mm):31.8 deg C):25.0	Coning Rate (Hz) -3.00 -3.00 -3.50 -4.50 -10.50 -11.50 -10.50 -7.80 -7.80 -7.80 -7.80 -7.80	•
File Gage Radius Room(CYI TY	Run 1 2 6 8 4 3 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	

TABLE 10a. Prograde Oscillatory Pressure Data for Re = 7.3, α = 2.00°, r/a = 0.667

: 100 :: 21.2 n: 2 :7.3	× C i	0.059	90	.10	.12	.15	.16	.17	.20	. 22	.20	. 17	.16	. 15	. 12	.10	.08	.06	• 05
11 Ratio(%) Sition (mm) annl Id Num ynolds Num:	ش م	0.053	6.5	.09	.11	. 14	. 15	• 16	. 19	. 21	. 18	• 16	. 15	. 13	. 11	• 00	.07	.05	.04
148 Fi. 838 Pos • 00 Cha 969 Rey	Ain Cp	0.046	. 06	.08	. 10	.13	. 14	.15	.17	. 19	.17	. 14	. 14	. 12	.10	.08	90.	.04	4
<pre>Rat(C/A):3. pt(psi):-1.1 g Ang(deg):2 ty(gm/cc): . Volt(V DC):1</pre>	Pressure Dynes/cm^2		.94E+0	.28E+0	.64E+0	.24E+0	.02E+0	.07E+0	.26E+0	.40E+0	.25E+0	.06E+0	.00E+0	.14E+0	.46E+0	.01E+0	.76E+0	.58E+0	.07E+0
0 Aspet 2 Intro 7 Conin K Densi Gage	ا بہ. ب	649	14	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
Freq(Hz): 70. (psi/mV): 772 ad (R/A): .66 sity(cs): 60 n:Prograde	de ms)	.02	042	.054	990.	. 079	.087	.091	.108	.120	.107	.090	.086	.078	.064	.051	.041	.030	.026
Spin E Slope (Pos/Re Viscos Motior	Tau		90	.07	• 09	.11	. 12	. 12	. 15	.16	.15	.12	. 12	.11	• 00	.07	.06	.05	.04
Name:G1B014 ID Num: 33 IS (mm):31.8 deg C):25.0 ype: Lucite	Coning Rate (Hz)	3.00	4.50	•	•	•	•	•	0	•	•	•	•	•	•	•	•	3.50	•
File Gage Radiu Room(Run	н (7 M	4	ហ	9	7	æ	σ	10	11	12	13	14	15	16	11	18	19

TABLE 10h. Retrograde Oscillatory Pressure Data for Re = 7.3, α = 2.00°, r/a = 0.667

(8):100 mm):21.2 Jum:2 um:7.3	Aax
ll Ratio(%) Sition (mm) annl Id Aur ynolds Num:	© D D D D D D D D D D D D D D D D D D D
.148 Fi 1838 Po 2.00 Ch .969 Re	Ain 0.00 0.047 0.066 0.053 0.053 0.120 0.120 0.120 0.120 0.120 0.120 0.120 0.042 0.062
<pre>cct Rat(C/A):3 rcpt(psi):-1. ing Ang(deg): isity(gm/cc): ie Volt(V DC):</pre>	Pressure Dynes/cm ² 2.70E+03 3.06E+03 3.06E+03 4.69E+03 6.77E+03 6.77E+03 7.24E+03 8.65E+03 6.75E+03 6.75E+03 7.22E+03 8.65E+03 8.65E+03 7.22E+03 8.65E+03 8.65E+03 7.22E+03 8.65E+03 8.65E+03 7.22E+03 8.65E+03 8.65E+03
.0 Aspet 22 Intro 67 Conin 0K Densi Gage	VO D C C C C C C C C C C C C C C C C C C
<pre>freq(Hz): 70 (psi/mV):.77 ad (R/A): .6 sity(cs): 6 n: Retrograde</pre>	Amplitude (Volts rms) 0.0233 0.0264 0.0366 0.0405 0.0585 0.0585 0.0624 0.0747 0.0819 0.0745 0.0531 0.0531 0.0531 0.0531
5 Spin 1 3 Slope 8 Pos/Ra 0 Viscos e Motion	Tau -0.043 -0.050 -0.050 -0.050 -0.121 -0.150 -0.150 -0.150 -0.150 -0.050
Name:GlB01 ID Num: 3 s (mm):31. deg C):25.	Coning Rate (Hz) -3.00 -3.00 -3.50 -4.50 -5.50 -6.50 -10.50 -11.50 -11.50 -7.80 -6.50 -7.80 -7.80 -7.80
File Gage Radiu Room(CY1 T	Run 1 1 2 8 4 3 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

TABLE 11a. Prograde Oscillatory Pressure Data for Re = 5.2, α = 2.00° , r/a = 0.667

():100 ():21.2 (m:2	Σ€Ω α α ×	.07	0.088	. 14	.16	.21	.23	. 24	. 29	.33	.30	. 24	.23	.20	•16	.13	.11	.08	.07
I Ratio(8 ition (mm innl Id Num	ئ ت	90.	0.076	. 12	. 15	. 19	. 21	. 22	. 27	.31	. 27	. 22	. 21	. 18	.15	. 12	.09	.07	90.
.148 Fil 1838 Pos 2.00 Cha .969 Rey 10.0	Ain Cp	.05		.11	.13	.17	. 19	. 20	. 25	. 28	. 25	.21	. 19	.16	.13	.11	.08	90.	.05
<pre>c Rat(C/A):3 cpt(psi):-1. ng Ang(deg): ity(gm/cc):</pre>	Pressure Dynes/cm^2	.15E+0	2.55E+03 3.29E+03	. 29E+0	.06E+0	.42E+0	.15E+0	.65E+0	.12E+0	.04E+0	.33E+0	.68E+0	.08E+0	.24E+0	.03E+0	.19E+0	.25E+0	.52E+0	.08E+0
.0 Aspet 22 Intro 67 Conir 0K Densi Gage	Voltage Gain	(1)		(1)	C	$\boldsymbol{\alpha}$	m	3	~	~	~	m	\sim	3	\sim	m	C	3	\mathbf{c}
<pre>Freq(Hz): 50 (psi/mV):.77 ad (R/A): .6 sity(cs): 6 n:Prograde</pre>	Amplitude (Volts rms)	.018	0.0217	.036	.042	.054	.060	.064	. 076	.086	.078	.064	.059	.052	.042	.035	.027	.021	. 017
Spin Slope Pos/Ra Viscos	Tau	90.	0.070	.11	.13	. 15	. 17	. 18	.21	.23	. 21	. 18	. 17	. 15	.13	. 11	• 09	.07	90.
Name:G3B012 ID Num: 33 us (mm):31.8 (deg C):25.0 Type: Lucite	Coning Rate (Hz)	3.00	3.50	•	6.50	•	8.50	•	•	•	0	•	•	•	6.50	•	•	3.50	•
File Gage Radius Room(CY1 T	Run	1	۳ م	4	ഗ	9	7	ထ	6	10	11	12						18	

TABLE 11b. Retrograde Oscillatory Pressure Data for Re = 5.2, α = 2.00°, r/a = 0.667

Σ ΧΩ α σ, ×	1 1 1	-0.045	-0.051	•	-0.083	-0.093	-0.106	-0.116	-0.122	-0.131	-0.143	-0.127	-0.118	-0.110	-0.106	-0.088	.07	-0.069	-0.051	-0.046
လ စ	! ! ! !	-0.054	-0.061	-0.081	-0.094	-0.106	-0.119	-0.130	-0.135	-0.146	-0.159	-0.142	-0.132	-0.124	0	-0.100	-0.090	-0.080	-0.061	-0.055
AXO n o	1 1 1	-0.065	-0.071	-0.093	-0.107	-0.119	-0.134	-0.145	-0.151	\mathbf{c}	-0.175	-0.157	-0.147	-0.138	-0.134	-0.114	-0.102	-0.092	-0.071	990.0-
Pressure Dynes/cm ² 2	t i i i i i i i i i i i i i i i i i i i	.83	.04	2.74E+03	.17E	. 55	2E	.36E	. 55E	ω	.33	.76	.43E	.15	2 E	.38	.01	.70	2.04E+03	8
Voltage Gain	1	4	4	4	645	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4.
Amplitude (Volts rms)	1 1 1 1 1	•	•	•	0.0272	•	•	•	•	•	•	•	•	•	•	•	•	•	0.0174	•
Tau	1 1 1	90.	-0.070	0	0	0	0	-0.170	0	0	0	Q	0	0		0		• 00	0	-0.060
Coning Rate (Hz)	!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!	-3.00	-3,50	•	-5.50	•	•	-8.50	•	0	_	_	00.6-	-	_	•	-5.50	•	-3.50	-3.00
Run	1	-	2	٣	₩	S	9	7	ω	6	10	11	12	13	14	15	16	17	18	19

TARLE 12a. Prograde Oscillatory Pressure Data for Re = 3.1, α = 2.00°, r/a = 0.667

):100):21.2 m:2 :3.1	¥ C₁		. 19	. 26	.31	.39	. 43	. 47	. 57	• 68	. 57	. 47	.43	.38	.30	.27	.20	.16	. 14
l Ratio(%) ition (mm) innl Id Num nolds Num:	d d	0.116	16	. 22	. 27	. 34	.39	. 42	. 52	.62	.51	. 42	.39	.33	. 26	. 23	.17	.13	. 11
148 Fil 833 Pos 2.00 Cha 969 Rey	Ain	0.089	13	. 19	. 23	.30	. 34	. 37	.47	. 56	.46	. 37	. 34	. 29	.23	. 19	. 14	. 10	• 08
<pre>Rat(C/A):3. pt(psi):-1.1 ng Ang(deg):2 ty(gm/cc): . Volt(V DC):1</pre>	Pressure Dynes/cm^2	1.40E+03	.00E+0	.74E+0	.32E+0	.19E+0	.7 3E+0	.09E+0	.32E+0	.53E+0	.24E+0	.09E+0	.73E+0	.11E+0	.24E+0	.81E+0	.08E+0	.59E+0	.36E+0
0 Aspet 2 Intro 7 Conin K Densi Gage	Voltage Gain		8	7	7	9	S	S	4	\sim	4	S	S	ø	~	~	œ	$\boldsymbol{\omega}$	Ø.
Freq(Hz): 30.(psi/mV):.772; ad (R/A): .665 sity(cs): 608 n:Prograde	ude rms) -	0.0110	.015	.021	.025	.031	.035	.037	.045	.053	.044	.037	.035	.030	.024	.021	.016	.012	.010
Spin E Slope(Pos/Ra Viscos Motion	Tau	101	. 15	. 18	.21	. 26	. 23	.30	.35	.38	.35	.30	.28	.26	.21	. 18	. 15	.11	10
Name:G3B010 ID Num: 33 Is (mm):31.8 deg C):25.0 ype: Lucite	Coning Rate (Hz)	3.00	•	5.50	.5	ω.		٥.	0.5	'n	0.5	0	.5	φ,	.5	.5		.5	٥.
File Gage Radiu Room(Run	٦,	m	4	5	9	7	ထ	6	10	11	12	13	14	15	16	11	18	19

TABLE 12b. Retrograde Oscillatory Pressure Data for Re = 3.1, α = 2.00°, r/a = 0.667

%):100 n):21.2 Jm:2 m:3.1	Cp
ll Ratio(% sition (mm annl Id Nu ynolds Num	© p -0.084 -0.087 -0.123 -0.137 -0.181 -0.181 -0.181 -0.181 -0.181 -0.181 -0.181 -0.181
.143 Fi. 1338 Pos 2.00 Chs .969 Rey 10.0	CAin -0.1111 -0.152 -0.152 -0.213 -0.213 -0.213 -0.213 -0.213 -0.213 -0.213 -0.213
<pre>Pat(C/\lambda):3 pt(psi):-1. f Ang(deg): ty(gm/cc): Volt(V DC):</pre>	Pressure Dynes/cm ² 1.02E+03 1.05E+03 1.05E+03 1.05E+03 2.23E+03 2.23E+03 2.29E+03 2.29E+03 2.29E+03 2.19E+03 2.19E+03 2.19E+03 2.19E+03 2.19E+03 1.92E+03 1.92E+03 1.05E+03 1.05E+03
O Aspet 22 Intro 37 Conin 37 Gage	Voltage Gain 510 612 626 629 625 625 625 625 625 625 625 625 625 625
Freq(Hz): 30. (psi/mV):.772 ad (R/A): .66 sity(cs): 60 n:Petrograde	Amplitude (Volts rms) 0.0032 0.0035 0.0122 0.0137 0.0183 0.0183 0.0183 0.0183 0.0183 0.0183 0.0183 0.0183 0.0183
Spin Slope Pos/R Visco	Tau -0.100 -0.117 -0.117 -0.183 -0.283 -0.380 -0.383 -0.383 -0.283 -0.283 -0.283 -0.283 -0.217 -0.183
Name: 333011 ID Num: 33 s (mm): 31.8 deg C): 25.0 ype: Lucite	Coning Rate (Hz) -3.00 -3.50 -4.50 -5.50 -7.80 -10.50 -10.50 -10.50 -7.80 -7.80 -7.80 -7.80
File Gage Radiu Room(CY1 TY	Run 1 1 2 8 4 3 2 4 3 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

TABLE 13. Comparison of Experimental Data to Two Available Low Reynolds Number Theories for Re = 3.1

Reynolds Number: 3.1												
Fill Ratio (%): 100 c/a: 3.148 r/a: 0.667												
TAU	EXP	SPEVM*	UWISC									
-0.99999		-0.43679	-0.5263									
-0.800		-0.18061	-0.2306									
-0.600		-0.12147	-0.1180									
-0.400		-0.15983	-0.1614									
-0.383	-0.186	-0.16046	-0.1594									
-0.350	-0.190	-0.16010										
-0.300	-0.181	-0.15482	-0.1578									
-0.283	-0.185	-0.15186										
-0.260	-0.176	-0.14662										
-0.217	-0.159	-0.13359	-0.1384									
-0.183	-0.137	-0.12019										
-0.150	-0.123	-0.10394	-0.1164									
-0.117	-0.087	-0.08644	-									
-0.100	-0.084	-0.07575	-0.0797									
0.100	0.116	0.10025	0.1077									
0.117	0.132	0.11973										
0.150	0.166	0.15956	0.1742									
0.183	0.226	0.20209										
0.217	0.274	0.24866	0.2691									
0.260	0.346	0.31164										
0.283	0.391	0.34724										
0.300	0.421	0.37432	0.4081									
0.350	0.522	0.45818										
0.383	0.623	0.51677	0.5668									
0.400		0.54805	0.6045									
0.600		0.96860	1.0750									
0.800 1.48574 1.6560												
0.99999 2.15680 2.4040												
* N	umber of El	genvalues:	10									

TABLE 14. Comparison of Experimental Data to Two Available Low Reynolds Number Theories for Re = 8.7

Reynolds Number: 8.7												
Fill Ratio (%): 100 c/a: 3.148 r/a: 0.667												
TAU	EXP	SPEVM*	UWISC									
-0.99999		-0.71524	-0.8100									
-0.800_		-0.3902	-0.4550									
-0.600		-0.20929	-0.2303									
-0.400		-0.16214	-0.1679									
-0.200		-0.12099	-0.1277									
-0.150	-+	-0.0996	-0.1058									
-0.138	-0.120	-0.09363										
-0.126	-0.109	-0.08731	-0.0929									
-0.108_	-0.097	-0.07723										
-0.102	-0.090	-0.07369	-0.0787									
-0.094	-0.083	-0.06884										
-0.078	-0.070	-0.05867	-0.0629									
-0.066	-0.061	-0.05063										
-0.054	-0.050	-0.04224	-0.0453									
-0.042	-0.038	-0.03348										
-0.036	-0.032	-0.02897	-0.0310									
0.036	0.038	0.03227	0.0348									
0.042	0.047	0.03797										
0.054	0.060	0.04964	0.0537									
0.066	0.075	0.06170										
0.078	0.090	0.07412	0.0803									
0.094	0.111	0.09126	+									
0.102	0.121	0.09971	0.1086									
0.108	0.129	0.10680	-									
0.126	0.158	0.12754	0.1387									
0.138	0.175	0.14183										
0.150		0.15648	0.1704									
0.200		0.22160	0.2419									
0.400		0.54650	0.6020									
0.600		0.97159	1.0767									
0.800		1.49120	1.6610									
0.99999		2.08436	2.3109									
* N	umber of Ei	genvalues:	10									

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LIST OF SYMBOLS

a	Radius of container
c	Half height of cylinder
c/a	Aspect ratio of container
\hat{c}_p	Nondimensional pressure coefficient
P	Oscillating pressure magnitude
p	Spin rate of the container
Re	Reynolds number = a^2p/v
r/a	Radial position/container radius
α	Coning angle
ν	Liquid kinematic viscosity
ρ	Liquid Density
$\dot{\phi}_1$	Coning rate of the container
т	Ratio of coning rate to spin rate $(\dot{\phi},/p)$

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